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This guide is a compilation of about fifty of the most important physics formulas to know for the SAT Subject test in physics. (Note that formulas are *not* given on the test.) Each formula row contains a description of the variables or constants that make up the formula, along with a brief explanation of the formula.

Kinematics

$v_{\rm ave} = \frac{\Delta x}{\Delta t}$	$v_{ m ave} = { m average \ velocity}$ $\Delta x = { m displacement}$ $\Delta t = { m elapsed \ time}$	The definition of average velocity.
$v_{\rm ave} = rac{(v_{ m i} + v_{ m f})}{2}$	$v_{ m ave} = { m average \ velocity}$ $v_{ m i} = { m initial \ velocity}$ $v_{ m f} = { m final \ velocity}$	Another definition of the average velocity, which works when a is constant.
$a = \frac{\Delta v}{\Delta t}$	$a =$ acceleration $\Delta v =$ change in velocity $\Delta t =$ elapsed time	The definition of acceleration.
$\Delta x = v_{\rm i} \Delta t + \frac{1}{2} a (\Delta t)^2$	$\Delta x = ext{displacement}$ $v_{ ext{i}} = ext{initial velocity}$ $\Delta t = ext{elapsed time}$ $a = ext{acceleration}$	Use this formula when you don't have $v_{\rm f}$.
$\Delta x = v_{\rm f} \Delta t - \frac{1}{2} a (\Delta t)^2$	$\Delta x = ext{displacement}$ $v_{ ext{f}} = ext{final velocity}$ $\Delta t = ext{elapsed time}$ $a = ext{acceleration}$	Use this formula when you don't have v_i .

Kinematics (continued)

$v_{\rm f}^2 = v_{\rm i}^2 + 2a\Delta x$	$v_{ m f}={ m final\ velocity}$ $v_{ m i}={ m initial\ velocity}$ $a={ m acceleration}$ $\Delta x={ m displacement}$	Use this formula when you don't have Δt .
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Dynamics

F = ma	F = force m = mass a = acceleration	Newton's Second Law. Here, F is the net force on the mass m.
W = mg	W = weight $m = mass$ $g = acceleration due$ to gravity	The weight of an object with mass m . This is really just Newton's Second Law again.
$f = \mu N$	$f=$ friction force $\mu=$ coefficient of friction $N=$ normal force	The "Physics is Fun" equation. Here, μ can be either the kinetic coefficient of friction μ_k or the static coefficient of friction μ_s .
p = mv	p = momentum $m = mass$ $v = velocity$	The definition of momentum. It is conserved (constant) if there are no external forces on a system.

Dynamics (continued)

$\Delta p = F \Delta t$	$\Delta p = { m change}$ in momentum $F = { m applied}$ force $\Delta t = { m elapsed}$ time	$F\Delta t$ is called the <i>impulse</i> .
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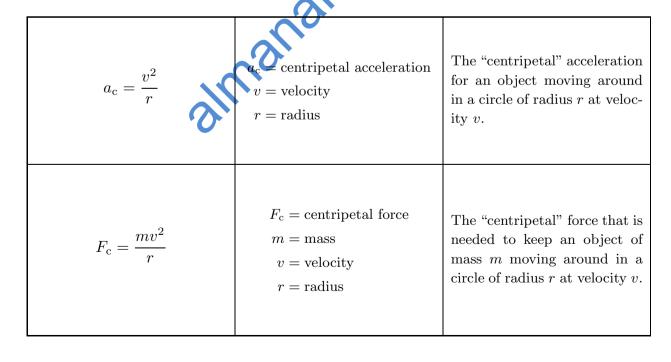
Work, Energy, and Power

$W = Fd\cos\theta$ or $W = F_{\parallel}d$	$W= { m work}$ $F= { m force}$ $d= { m distance}$ $ heta= { m angle between } F$ ${ m and the direction}$ of motion $F_{\parallel}= { m parallel force}$	Work is done when a force is applied to an object as it moves a distance d . F_{\parallel} is the component of F in the direction that the object is moved.
$KE = \frac{1}{2}mv^2$	KE = kinetic energy $m = mass$ $v = velocity$	The definition of kinetic energy for a mass m with velocity v .
$\mathrm{PE}=mgh$	PE = potential energy $m = mass$ $g = acceleration due$ to gravity $h = height$	The potential energy for a mass m at a height h above some reference level.

Work, Energy, Power (continued)

$W = \Delta(\mathrm{KE})$	W = work done $KE = kinetic energy$	The "work-energy" theorem: the work done by the <i>net</i> force on an object equals the change in kinetic energy of the object.
E = KE + PE	E = total energy $KE = kinetic energy$ $PE = potential energy$	The definition of total ("mechanical") energy. If there is no friction, it is conserved (stays constant).
$P = \frac{W}{\Delta t}$	$P = \text{power}$ $W = \text{work}$ $\Delta t = \text{elapsed time}$	Power is the amount of work done per unit time (i.e., power is the <i>rate</i> at which work is done).

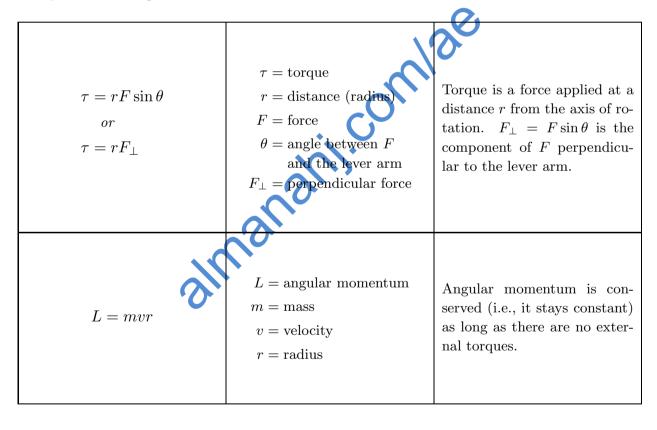
Circular Motion



Circular Motion (continued)

$v = \frac{2\pi r}{T}$	v = velocity $r = radius$ $T = period$	This formula gives the velocity v of an object moving once around a circle of radius r in time T (the period).
$f = \frac{1}{T}$	f = frequency $T = period$	The frequency is the number of times per second that an object moves around a circle.

Torques and Angular Momentum



Springs

$F_s = kx$	$F_s = \text{spring force}$ $k = \text{spring constant}$ $x = \text{spring stretch or compression}$	"Hooke's Law". The force is opposite to the stretch or compression direction.
$PE_s = \frac{1}{2}kx^2$	$PE_s = potential energy$ $k = spring constant$ $x = amount of$ $spring stretch$ $or compression$	The potential energy stored in a spring when it is either stretched or compressed. Here, $x=0$ corresponds to the "natural length" of the spring.

Simple Harmonic Motion

$T_s = 2\pi \sqrt{\frac{m}{k}}$	T_s = period of motion k = spring constant m = attached mass	The period of the simple harmonic motion of a mass m attached to an ideal spring with spring constant k .
$T_p = 2\pi \sqrt{rac{l}{g}}$	$T_p = \text{period of motion}$ $l = \text{pendulum length}$ $g = \text{acceleration due}$ to gravity	The period of the simple harmonic motion of a mass m on an ideal pendulum of length l .

Gravity

$F_g = G \frac{m_1 m_2}{r^2}$	$F_g = ext{force of gravity}$ $G = ext{a constant}$ $m_1, m_2 = ext{masses}$ $r = ext{distance of separation}$	Newton's Law of Gravitation: this formula gives the attractive force between two masses a distance r apart.
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Electric Fields and Forces

$F = k \frac{q_1 q_2}{r^2}$	$F={ m electric} \ { m force}$ $k={ m a} \ { m constant}$ $q_1,q_2={ m charges}$ $r={ m distance} \ { m of}$ separation	"Coulomb's Law". This formula gives the force of attraction or repulsion between two charges a distance r apart.
F = qE	F = electric force E = electric field q = charge	A charge q , when placed in an electric field E , will feel a force on it, given by this formula (q is sometimes called a "test" charge, since it tests the electric field strength).
$E = k \frac{q}{r^2}$	E = electric field $k = a constant$ $q = charge$ $r = distance of$ $separation$	This formula gives the electric field due to a charge q at a distance r from the charge. Unlike the "test" charge, the charge q here is actually generating the electric field.

Electric Fields and Forces (continued)

$U_E = k \frac{q_1 q_2}{r}$	$U_E = ext{electric PE}$ $k = ext{a constant}$ $q_1, q_2 = ext{charges}$ $r = ext{distance of}$ $ ext{separation}$	This formula gives the electric potential energy for two charges a distance r apart. For more than one pair of charges, use this formula for each pair, then add all the U_E 's.
$\Delta V = \frac{-W_E}{q} = \frac{\Delta U_E}{q}$	$\Delta V = ext{potential difference}$ $W_E = ext{work done by E field}$ $U_E = ext{electric PE}$ $q = ext{charge}$	The potential difference ΔV between two points is defined as the negative of the work done by the electric field per unit charge as charge q moves from one point to the other. Alternately, it is the change in electric potential energy per unit charge.
$V = k \frac{q}{r}$	$V = ext{electric potential}$ $k = ext{a constant}$ $q = ext{charge}$ $r = ext{distance of}$ $ ext{separation}$	This formula gives the electric potential due to a charge q at a distance r from the charge. For more than one charge, use this formula for each charge, then add all the V 's.
$E = \frac{V}{d}$	E = electric field $V = voltage$ $d = distance$	Between two large plates of metal separated by a distance d which are connected to a battery of voltage V , a uniform electric field between the plates is set up, as given by this formula.

Circuits

V = IR	V = voltage $I = current$ $R = resistance$	"Ohm's Law". This law gives the relationship between the battery voltage V , the current I , and the resistance R in a circuit.
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Circuits (continued)

$P = IV$ or $P = V^{2}/R$ or $P = I^{2}R$	P = power $I = current$ $V = voltage$ $R = resistance$	All of these power formulas are equivalent and give the power used in a circuit resistor R . Use the formula that has the quantities that you know.
$R_{\rm s} =$ $R_1 + R_2 + \dots$	$R_{\rm s}={ m total~(series)}$ ${ m resistance}$ $R_1={ m first~resistor}$ $R_2={ m second~resistor}$ \dots	When resistors are placed end to end, which is called "in series", the effective total resistance is just the sum of the individual resistances.
$\frac{1}{R_{\rm p}} =$ $\frac{1}{R_1} + \frac{1}{R_2} + \dots$	$R_{ m p}={ m total~(parallel)}$ resistance $R_1={ m first~resistor}$ $R_2={ m second~resistor}$ \ldots	When resistors are placed side by side (or "in parallel"), the effective total resistance is the inverse of the sum of the re- ciprocals of the individual re- sistances (whew!).
q = CV	q = charge $C = capacitance$ $V = voltage$	This formula is "Ohm's Law" for capacitors. Here, C is a number specific to the capacitor (like R for resistors), q is the charge on one side of the capacitor, and V is the voltage across the capacitor.

Magnetic Fields and Forces

$F = ILB\sin\theta$	$F = ext{force on a wire}$ $I = ext{current in the wire}$ $L = ext{length of wire}$ $B = ext{external magnetic field}$ $\theta = ext{angle between the}$ $ ext{current direction and}$ $ ext{the magnetic field}$	This formula gives the force on a wire carrying current I while immersed in a magnetic field B . Here, θ is the angle between the direction of the current and the direction of the magnetic field (θ is usually 90°, so that the force is $F = ILB$).
$F = qvB\sin\theta$	$F=$ force on a charge $q=$ charge $v=$ velocity of the charge $B=$ external magnetic field $\theta=$ angle between the direction of motion and the magnetic field	The force on a charge q as it travels with velocity v through a magnetic field B is given by this formula. Here, θ is the angle between the direction of the charge's velocity and the direction of the magnetic field (θ is usually 90°, so that the force is $F = qvB$).

Waves and Optics

$v = \lambda f$	$v = ext{wave velocity}$ $\lambda = ext{wavelength}$ $f = ext{frequency}$	This formula relates the wavelength and the frequency of a wave to its speed. The formula works for both sound and light waves.
$v = \frac{c}{n}$	v = velocity of light $c = vacuum light speed$ $n = index of refraction$	When light travels through a medium (say, glass), it slows down. This formula gives the speed of light in a medium that has an index of refraction n . Here, $c = 3.0 \times 10^8$ m/s.

Waves and Optics (continued)

$n_1 \sin \theta_1 = n_2 \sin \theta_2$	$n_1 = ext{incident index}$ $ heta_1 = ext{incident angle}$ $n_2 = ext{refracted index}$ $ heta_2 = ext{refracted angle}$	"Snell's Law". When light moves from one medium (say, air) to another (say, glass) with a different index of refraction n , it changes direction (refracts). The angles are taken from the normal (perpendicular).
$\frac{1}{d_{\rm o}} + \frac{1}{d_{\rm i}} = \frac{1}{f}$	$d_{ m o}={ m object\ distance}$ $d_{ m i}={ m image\ distance}$ $f={ m focal\ length}$	This formula works for lenses and mirrors, and relates the focal length, object distance, and image distance.
$m = -\frac{d_{\rm i}}{d_{\rm o}}$	$m={ m magnification}$ $d_{ m i}={ m image}$ distance $d_{ m o}={ m object}$ distance	The magnification m is how much bigger $(m > 1)$ or smaller $(m < 1)$ the image is compared to the object. If $m < 0$, the image is inverted compared to the object.

Heat and Thermodynamics

$Q=mc\Delta T$	$Q=$ heat added or removed $m=$ mass of substance $c=$ specific heat $\Delta T=$ change in temperature	The specific heat c for a substance gives the heat needed to raise the temperature of a mass m of that substance by ΔT degrees. If $\Delta T < 0$, the formula gives the heat that has to be $removed$ to lower the temperature.
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Heat and Thermodynamics (continued)

Q = ml	Q = heat added or removed $m = mass of substance$ $l = specific heat$ of transformation	When a substance undergoes a change of phase (for example, when ice melts), the temperature doesn't change; however, heat has to be added (ice melting) or removed (water freezing). The specific heat of transformation l is different for each substance.
$\Delta U = Q - W$	$\Delta U = ext{change in}$ $internal energy$ $Q = ext{heat added}$ $W = ext{work done}$ $by the system$	The "first law of thermodynamics". The change in internal energy of a system is the heat added minus the work done by the system.
$E_{\mathrm{eng}} = \frac{W}{Q_{\mathrm{hot}}} \times 100$	$E_{ m eng} = \%$ efficiency of the heat engine $W \neq { m work}$ done by the engine $Q_{ m hot} = { m heat}$ absorbed by the engine	A heat engine essentially converts heat into work. The engine does work by absorbing heat from a hot reservoir and discarding some heat to a cold reservoir. The formula gives the quality ("efficiency") of the engine.

Pressure and Gases

Pressure and Gases (continued)

by the temperature of the is a constant.	$\frac{PV}{T} = \text{constant}$	P = pressure $V = volume$ $T = temperature$	The "Ideal Gas Law". For "ideal" gases (and also for real-life gases at low pressure), the pressure of the gas times the volume of the gas divided by the temperature of the gas is a constant
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Modern Physics and Relativity

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E=hf	E = photon energy $h = a constant$ $f = wave frequency$	The energy of a photon is proportional to its wave frequency; h is a number called "Planck's constant".
$ ext{KE}_{ ext{max}} = hf - \phi$	$KE_{max} = max$ kinetic energy $h = a$ constant $f = light$ frequency $\phi = work$ function of the metal	The "photoelectric effect" formula. If light of frequency f is shined on a metal with "work function" ϕ , and $hf > \phi$, then electrons are emitted from the metal. The electrons have kinetic energies no greater than KE_{max} .
$\lambda = \frac{h}{p}$	$\lambda = ext{matter wavelength}$ $h = ext{a constant}$ $p = ext{momentum}$	A particle can act like a wave with wavelength λ , as given by this formula, if it has momentum p . This is called "waveparticle" duality.
$\gamma = \frac{1}{\sqrt{1 - (v/c)^2}}$	$\gamma =$ the relativistic factor $v =$ speed of moving observer $c =$ speed of light	The relativistic factor γ is the amount by which moving clocks slow down and lengths contract, as seen by an observer compared to those of another observer moving at speed v (note that $\gamma \geq 1$).